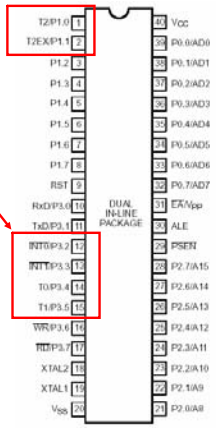
Microprocessors 1

Timers/Counters

Reminder

- The pins of port 3 have dual functionality.
  - These second functions are mostly related to the timers.
- For the 8052, 2 pins on port 1 also have additional functionality related to timers.



The MCS-51 Timers

- The 8051 has two registers that can be used either as timers or counters.
  - These are referred to as Timer0 and Timer1.
- These timers exist in the SFR area as pairs of 8-bit registers.
  - TL0 (8AH) and TH0 (8CH) for Timer0.
  - TL1 (8BH) and TH1 (8DH) for Timer1.
  - LSB is bit 0 of TLx and MSB is bit 7 of THx.
- The 8052 has a third timer called Timer 2.
  - TL2 (CCH) and TH2 (CDH).

Usage

- The timers can be used for:
  - Interval timing
    - The timer is programmed to overflow at a regular interval and set the timer overflow flag.
      - Overflow means reaching maximum count of FFFFH.
  - Event counting
    - Determine the number of occurrences of an event. An event is any external stimulus that provides a 1-to-0 transition on a pin of the 8051.
  - Baud rate generation for the built-in serial port.

Incrementing

- When used as timers, the registers are incremented once per machine cycle.
  - Each machine cycle is 12 clock cycles.
    - The count frequency = (system clock frequency) / 12
- When used as counters, the registers will be incremented once on every 1-0 (negative edge) on the appropriate input pin.
  - T0 – P3.4
  - T1 – P3.5
  - The pins must be held high for one complete machine cycle and then low for one complete machine cycle.

Timer Mode Register

- The TMOD register (89H) contains two groups of 4 bits that set the operating mode for Timer 0 and Timer 1.

Bit	Name	Description
7	GATE	Gate bit. If set, timer 1 will only increment while $\overline{INT1}$ is high.
6	C/$\overline{T}$	Counter/timer select bit 1 = event counter – external timing signal 0 = interval timer – internal timing signal
5	M1	Mode bit 1
4	M0	Mode bit 0
3	GATE	Timer 0 Gate bit
2	C/T	Timer 0 counter/timer select bit
1	M1	Timer 0 M1 bit
0	M0	Timer 0 M0 bit

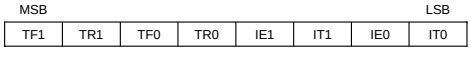
Timer Mode Definitions

- Using the M1 and M0 bits of the TMOD register, we can set the timers to operate in one of 4 possible modes:

M1	M0	Mode	Description
0	0	0	13-bit timer mode
0	1	1	16-bit timer mode
1	0	2	8-bit auto reload mode
1	1	3	Split timer mode: Timer 0: TL0 is an 8-bit timer controlled by timer 0 mode bits; TH0 the same except controlled by timer 1 mode bits. Timer 1: Stopped.

Timer Control Register

- The TCON register (88H) contains status and control bits for Timer0 and Timer1.
  - Bit addressable.



Bit	Name	Description
TCON.7	TF1	Timer 1 overflow flag
TCON.6	TR1	Timer 1 run-control bit. Used to turn the timer on/off
TCON.5	TF0	Timer 0 overflow flag
TCON.4	TR0	Timer 0 run-control bit.
TCON.3	IE1	External Interrupt 1 edge flag
TCON.2	IT1	External Interrupt 1 type flag
TCON.1	IE0	External Interrupt 0 edge flag
TCON.0	IT0	External Interrupt 0 type flag

Mode 0/1

- In mode 1, the timer/counter is configured as a 16-bit timer/counter.
  - The upper 8 bits of the count are in TH
  - The lower 8 bits are in TL.
- In mode 0, the timer/counter is configured as a 13-bit timer/counter.
    - Used for backward compatibility with the 8048.
  - The upper 8 bits of the count are in TH
  - The lower 5 bits are in the lower 5 bits of TL.
  - The upper 3 bits of TL are not used
- The TFx flag will be set when the counter switches from all 1's to all 0's.
  - The timer continues to count.

Mode 2

- 8-bit Auto-Reload Mode
  - TL operates as an 8-bit counter.
  - TH holds a reload value.
    - When TL overflows (reached FFH), the TFx flag is set, TL is reloaded from the value in TH and counting continues.
  - To make counter 0 count 40H times:
    - Set TH0 to BFH
    - Set the counter to mode 2.
    - Run the counter.
    - Once it reached FFH, it will reload with BFH and repeat.

Mode 3

- Split timer mode.
- Timer 0 is split into two independent 8-bit timers.
  - When TL0 overflows, it sets the TF0 flag.
  - When TH0 overflows, it sets the TF1 flag.
- Timer 1 is stopped in mode 3.
  - It can be switched independently to a different mode.
    - However, when it overflows it will NOT set the TF1 flag.

Clocking Sources

- There are two possible clock sources for the timers controlled by the C/$\overline{T}$ bit of each timer in the TMOD register.
- If C/$\overline{T}$ = 0, continuous timer operation is selected and the timer is clocked from by the system clock divided by 12.
  - The timer is being used for interval timing.
  - Timer overflow occurs after a certain number of cycles depending on the initial value stored in TLx/THx.
- If C/$\overline{T}$ = 1, the timer is clocked from an external source (pin T0 or T1 on port 3).
  - The timer is being used for event counting.
  - The number of events is stored as a 16-bit hexadecimal value in TLx/THx.

Starting, Stopping and Controlling the Timers

- The simplest method for starting and stopping the timers is by setting/clearing the TRx bit in TCON.
  - TRx is cleared after a reset.
    - It has to be set by software to start the timer.
  - TCON is bit addressable.
    - SETB TR0
    - CLR TR0

Starting, Stopping and Controlling the Timers

- The other possibility is by using the GATE bit of TMOD and the external input $\overline{INT}$x.
  - Setting GATE = 1 allows the timer to be controlled by $\overline{INT}$x.
    - When $\overline{INT}$x goes high, the counter is enabled and counts at a rate of system clock/12.
    - When $\overline{INT}$x goes low, the counter is disabled.

Initializing the Timer Registers

- TMOD is the first register initialized since it sets the mode of operation.

```
MOV   TMOD, #00010000B
```

  - This sets Timer 1 into mode 1 clocked from the on-chip oscillator.
- An initial value is stored in THx/TLx if necessary.

```
MOV   TL1, #9CH
MOV   TH1, #0FFH
```

  - This will set the starting value of Timer1 to FF9CH.
    - Timer1 will count 100 cycles before overflowing.
- To start the timer, we need to set the right TRx bit.

```
SETB  TR1
```


Monitoring the Timer

- It is possible to write an ISR that responds when the timer overflows. Then we can enable the appropriate interrupt bit in the IE register and let the microcontroller respond automatically.
- Or, we can write a wait loop and monitor the timer flag TFx.

```
WAIT:  JNB   TF1, WAIT
```

  - When the counter reaches FFFFH and turns to 0000H, the TF1 bit will be set and the program will break out of the loop.

Responding to a Timer Overflow

- When the timer overflows, we need to stop it and then reset the TFx bit so that we don't generate false overflows.

```
CLR     TR1
CLR     TF1
```